

What is claimed is:

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1. A vehicle control system comprising a plurality of control devices which forms a plurality of subsystems connected to respective controlled objects and a cooperative control device which cooperatively operates said plurality of control devices through a communication line, wherein

5 each of said plurality of control devices comprises an input/output control device for conducting input and output processing for the signals sent and received between said cooperative control devices and said controlled objects; and

10 said cooperative control device comprises a control calculation device for calculating control signals which control operations of said plurality of control devices and said controlled objects based on the received signals that have been received from said plurality of control devices.

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2. A vehicle control system according to claim 1 wherein

5 said control calculation device of said cooperative control device calculates controlled physical values to be attained by operations of said plurality of control devices and said controlled objects as control signals which control the operation of said plurality of control devices and said controlled objects; and

10 said input/output control devices of said control system convert said controlled physical values which have been received from said cooperative control device to operation command values that indicate directly the operation of said control devices and said controlled objects.

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3. A vehicle control system according to either claim 1 or claim 1, wherein

said plurality of control devices provides an autonomous control device which controls the operations of said controlled objects independently from said cooperative control device during the occurrence of an abnormality between said communication systems and said cooperative control devices or said cooperative control device.

4. A vehicle control system comprising a plurality of control devices which forms a plurality of subsystems connected to respective controlled objects and a cooperative control device which cooperatively operates said plurality of control devices through a communication line, wherein the vehicle control system further comprises:

5 a priority assigning device which assigns a priority to the data sent and received
via said communication lines;

10 a plurality of FIFO storage devices which temporarily store said data after being
classified depending on said priority; and

15 a data sending device which sends said data according to its priority from said
FIFO storage device which stores said data having high priority.

5. A vehicle control system according to claim 4, wherein, said data sending device which sends data according to its priority stops transmission of said data being sent when the data with an priority that is higher than said data being sent is stored in said FIFO storage device and sends said data having the higher priority.

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6. A vehicle control system according to claim 4, further comprises,
a packet generating device that generates packets as said data and a message
generating device that partitions said packets into messages depending on the
communication protocol; wherein

5 said priority assigning device assigns said priority depending on the length of
said packet;

 said plurality of FIFO storage devices classify and temporarily store said
message depending on said priority of said packets; and

10 said data transmission device sends said message according to the priority from
said FIFO storage device that stores said packets assigned said high priority.

7. A vehicle control system comprising a plurality of control devices which forms a
plurality of subsystems connected to respective controlled objects and a cooperative
control device which cooperatively operates said plurality of control devices through a
communication line, wherein the vehicle control system further comprises:

5 said cooperative control device comprises;

 a plurality of different cooperative control side communication ports,
 a data sending and receiving device that carries out transmission and
receiving of data to and from said plurality of control devices through said cooperative
control side communication ports, and

10 a determination device that determines whether or not an abnormality has
occurred in the transmission and receiving of said data; and wherein,

 said plurality of control devices each comprise a plurality of communication
ports that connect at least two or more among said plurality of cooperative control side
communication ports; and

15 said data sending and receiving device of said cooperative control device,
depending on the results of the determination by the determination device, sends and
receives different said data to and from each of said plurality of communication ports of
said control devices, and in addition, said data sent to and received from said

communication ports where said abnormality has occurred is sent to and received from
20 any said communication ports where said abnormality has not occurred.

8. A vehicle control system comprising a plurality of control devices which forms a plurality of subsystems connected to respective controlled objects and a cooperative control device which cooperatively operates said plurality of control devices through a communication line, wherein the vehicle control system further comprises:

5 a plurality of different cooperative control side communication ports,
a data sending and receiving device that sends and receives data to and from
said plurality of control device through said cooperative control side communication
ports, and
a determination device that determines whether or not an abnormality has
10 occurred in the sending or receiving of said data, and a data partitioning devices that
generates a plurality of segments of partitioned data by partitioning said data according
to the results of the determination by said determination device; and
said plurality of control devices each comprises a plurality of communication
ports that connect at least two or more of said plurality of cooperative control side
15 communication ports; and furthermore:
said data sending and receiving device of said cooperative control device sends
and receives said different data to and from each of said plurality of communication
ports of said control device depending on the result of the determination of said
determination apparatus, and in addition, said plurality of partitioned data is sent and
20 received by being distributed over said plurality of communication ports on which no
abnormality has occurred.

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